

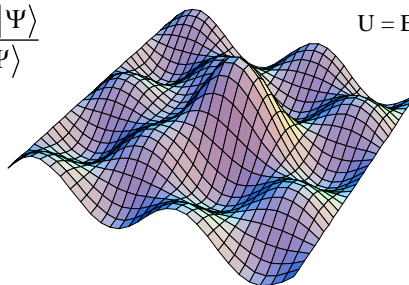
# Molecular Simulation II

Quantum Chemistry

$$E = \frac{\langle \Psi | H | \Psi \rangle}{\langle \Psi | \Psi \rangle}$$

Classical Mechanics

$$U = E_{\text{bond}} + E_{\text{angle}} + E_{\text{torsion}} + E_{\text{non-bond}}$$



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## Classical Mechanical Treatment

### I. Classical Mechanics

- a. Implicit treatment of electrons
- b. Use simple analytical functions (i.e., harmonic springs)
- c. Use Cartesian coordinates, not the z-matrix

### II. Force Fields

- a. Have evolved over time
- b. Use different analytical terms and parameters
- c. Are specific for classes of molecules (proteins, carbohydrates, nucleic acids, organic molecules, etc.)

## Force Field

- What is a force field?
  - A mathematical expression that describes the dependence of the energy of a molecule on the coordinates of the atoms in the molecule
  - Also this sometimes used as another term for potential energy function.
- What are force fields used for?
  - Structure determination
  - Conformational energies
  - Rotational and Pyramidal inversion barriers
  - Vibrational frequencies
  - Molecular dynamics

## Force Field History

- Pre-1970
  - Harmonic
- 1970
  - For molecules with less than 100 atoms one class of force fields went for high accuracy to match experimental results
  - The other class of force fields was for macromolecules.
- Present
  - There are highly accurate force fields designed for small molecules and there are force fields for studying protein and other large molecules

## Force Field

- First force fields developed from experimental data
  - X-ray
  - NMR
  - Microwave
- Current force fields have made use of quantum mechanical calculations
  - CFF
  - MMFF94
- There is no single “best” force field

## Force Fields

- **MM2/3/4**: Molecular Mechanic Force field for small molecules
- **CHARMM**: Chemistry at Harvard Macromolecular Mechanics
- **AMBER**: Assisted Model Building with Energy Refinement
- **OPLS**: Optimized Parameters for Liquid Simulation
- **CFF**: Consistent Force Field
- **CVFF**: Valence Consistent Force Field
- **MMFF94**: Merck Molecular Force Field 94
- **UFF**: Universal Force Field

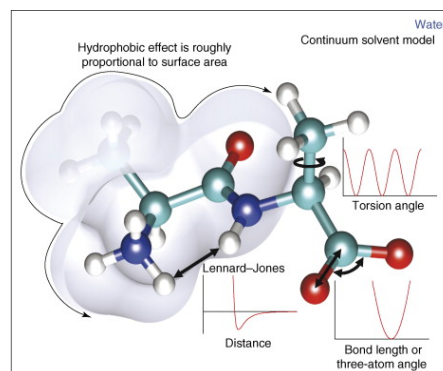
# Comparison and Evaluation

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# Potential Energy Function

The potential energy function is a mathematical model which describes the various interactions between the atoms of a molecule or system of molecules. In general, the function is composed of *intramolecular terms* (1st three terms) and *intermolecular terms* (last two terms).

$$\begin{aligned}
 U(r) = & \frac{1}{2} \sum (b - b_0)^2 + \\
 & \frac{1}{2} \sum (\theta - \theta_0)^2 + \\
 & \frac{1}{2} \sum_j V_j [1 + (-1)^{j+1} \cos(n_j \phi - \delta)] + \\
 & 4\epsilon \left[ \left( \frac{\sigma}{r_{ij}} \right)^{12} - \left( \frac{\sigma}{r_{ij}} \right)^6 \right] + \\
 & \frac{q_i q_j}{4\epsilon r_{ij}}
 \end{aligned}$$



Curr. Opin. Struct. Bio. 2007, 17, 199

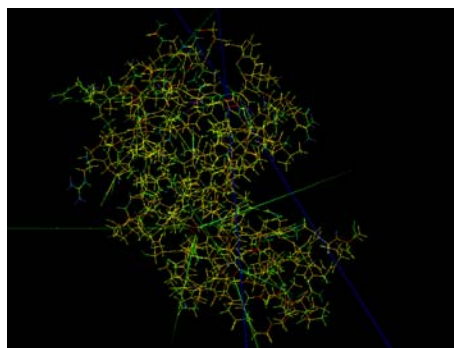
## Molecular Mechanics

In the molecular mechanics model, a molecule is described as a series of point charges (atoms) linked by springs (bonds). A mathematical function (the force-field) describes the freedom of bond lengths, bond angles, and torsions to change. The force-field also contains a description of the van der Waals and electrostatic interactions between atoms that are not directly bonded. The force-field is used to describe the potential energy of the molecule or system of interest. Molecular mechanics is a mathematical procedure used to explore the potential energy surface of a molecule or system of interest.

Force

$$\mathbf{F} = -\nabla U$$

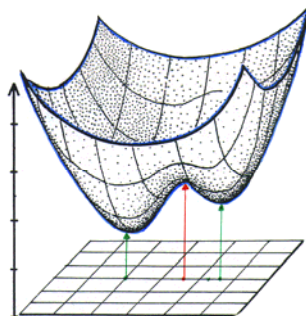
Potential Energy



## Potential Energy Minimizations

- **Potential Energy Surface:** Has minima (stable structures) and saddle points (transition states).

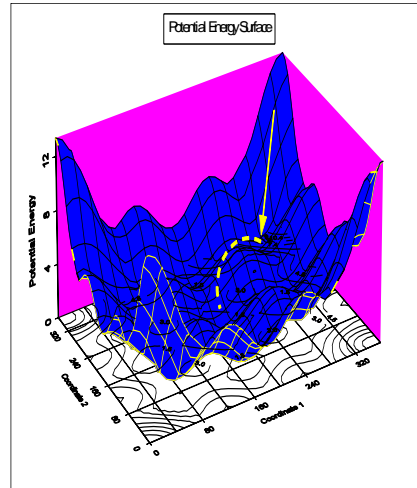
*Below:* 2 minima & 1 Saddle Point.



# Energy Minimization

Given a function  $f$  which depends on one or more independent variables,  $x_1, x_2, \dots$ , find the values of those variables where  $f$  has a minimum value.

$$\frac{\partial f}{\partial x_i} = 0$$
$$\frac{\partial^2 f}{\partial x^2} > 0$$



## Energy Minimization Methods

- Taylor series expansion about point  $x_k$

$$U(x) = U(x_k) + (x - x_k) \frac{\partial U(x_k)}{\partial x_k} + \frac{(x - x_k)^2}{2} \frac{\partial^2 U(x_k)}{\partial x_k \partial x_j} + \dots$$

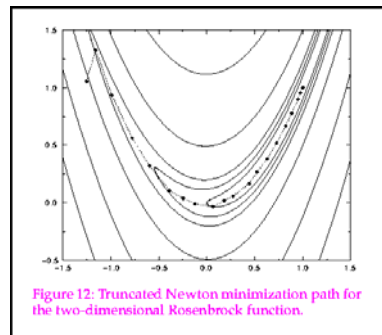
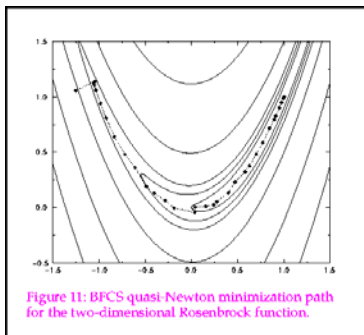
- the second term is known as the **gradient** (force)
- the third term is known as the **Hessian** (force constant)
- Algorithms are classified by **order**, or the highest derivative used in the Taylor series.
- Common algorithms (1<sup>st</sup> Order): Steepest Descent (SD), Conjugated Gradients (CONJ)
- Non-derivative
  - Simplex
  - Sequential univariate method

## Energy Minimization Methods

- Derivative
  - Steepest descents
    - Moves are made in the direction parallel to the net force
  - Conjugate gradient
    - The gradients and the direction of successive steps are orthogonal
  - Newton-Raphson
    - Second-order method; both first and second derivatives are used
  - BFGS
    - Quasi-Newton method (a.k.a. variable metric methods) build up the inverse Hessian matrix in successive iterations

## Energy Minimization Methods

- Truncated Newton-Raphson
  - Initially follow a descent direction and near the solution solve more accurately using a Newton method.
  - Different from QN in that the Hessian is sparse allowing for a faster evaluation



## Comparing 1<sup>st</sup> Order Algorithms

**BOTH:** iterate over the following equation in order to perform the minimization:  $\mathbf{R}_k = \mathbf{R}_{k-1} + l_k \mathbf{S}_k$

Where  $\mathbf{R}_k$  is the new position at step  $k$ ,

$\mathbf{R}_{k-1}$  in the position at the previous step  $k-1$ ,

$l_k$  is the size of the step to be taken at step  $k$  and  $\mathbf{S}_k$  is the direction.

**SD:** At each step the gradient of the potential  $\mathbf{g}_k$  (i.e., the first derivative in multi-dimensions) is calculated and a displacement is added to all the coordinates in a direction opposite to the gradient.  $\mathbf{S}_k = -\mathbf{g}_k$

**CONJ:** In each step, weights in the previous gradients to compensate for the lack of curvature information.

For all steps  $k > 1$  the direction of the step is a weighted average of the current gradient and the previous step direction, i.e.,

$$\mathbf{S}_k = -\mathbf{g}_k + b_k \mathbf{S}_{k-1}$$

## Comparison of Methods

- Convergence

- Small change in energy
- Small norm of the gradient
- RMS gradient

$$|grad| = \sqrt{\sum_i \left( \frac{dU}{dx_i} \right)^2}$$

$$RMS = \frac{|grad|}{\sqrt{n}}$$

- Number of steps vs. time

- Steepest descents: 500 steps in 41.08 secs (not converged)
- Conjugate gradient: 72 steps in 15.77 seconds
- Newton-Raphson: 15 steps in 14.84 seconds



## Which Method Should I Use?

- Must consider
  - **Storage:** Steepest descents little memory needed while Newton-Raphson methods require lots.
  - **Availability of derivatives:** Simplex, none are needed, steepest descents, only first derivatives, Newton-Raphson needs first and second derivatives.
- The following is common practice
  - SD or CG for the initial “rough” minimization followed by a few steps of NR.
  - SD is superior to CG when starting structure is far from the minimum
  - TN method after a few SD and/or CG appears to give the “best” overall and fastest convergence

## Conformational Analysis

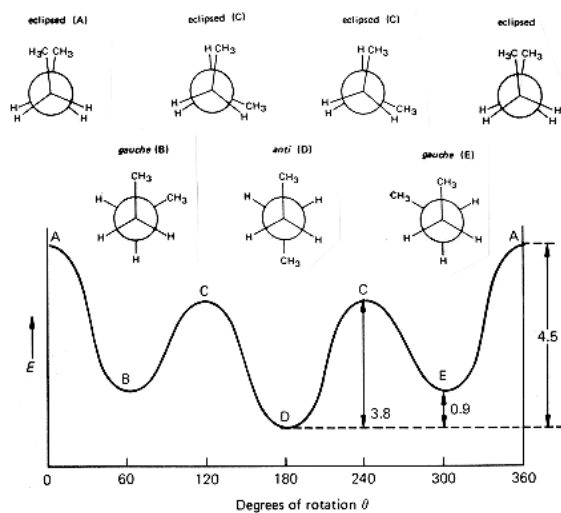
- Molecular conformations
  - term used to describe molecular structures that interconvert under ambient conditions.
  - this implies several conformations may be present, in differing conc., under ambient conditions.
  - a proper description of “the” molecular structure, “the” molecular energy, or “the” spectrum for a molecule with several conformations must comprise a proper weighting of all of the conformations.

## Boltzmann's equation

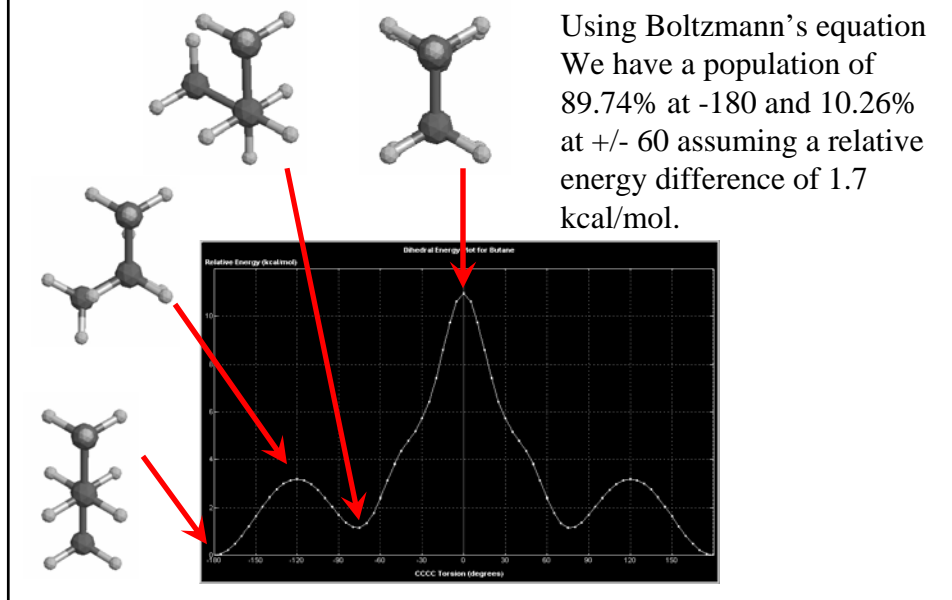
$$P_i = \frac{f_i e^{-\frac{E_i}{RT}}}{\sum_j f_j e^{-\frac{E_j}{RT}}}$$

- $f_i$  is the number of states or conf. of energy  $E_i$
- $R$  is 1.98 cal/mol-K (the ideal gas constant)
- $T$  is the absolute temperature (K)
- $j$  is the summation over all the conformations

## Butane Conformational Analysis



## Conformational Analysis Example



## Conformational Analysis: A Cautionary Note

Term	MM2			Dreiding		
	Trans	Gauche	$\Delta E$	Trans	Gauche	$\Delta E$
Stretch	0.15	0.16	0.01	0.33	0.38	0.05
Stretch-Bend	0.05	0.07	0.02			
Bend	0.29	0.63	0.34	0.51	1.15	0.64
Torsion	0.01	0.44	0.43	0.01	0.11	0.01
VDW	1.68	1.75	0.07	3.59	3.59	0.00
Total	2.18	3.05	<b>0.87</b>	4.44	5.23	<b>0.79</b>

Even though the energetic difference given by the two models is similar, different contributions give rise to those differences.